



ELSEVIER

Journal of Geometry and Physics 24 (1998) 244–264

JOURNAL OF  
GEOMETRY AND  
PHYSICS

# Invariants of velocities and higher-order Grassmann bundles <sup>★</sup>

Dan Radu Grigore <sup>1</sup>, Demeter Krupka <sup>\*</sup>

*Department of Mathematics, Silesian University at Opava, Bezručovo nám. 13,  
74601 Opava, Czech Republic*

Received 21 February 1996

---

## Abstract

An  $(r, n)$ -velocity is an  $r$ -jet with source at  $0 \in \mathbb{R}^n$ , and target in a manifold  $Y$ . An  $(r, n)$ -velocity is said to be regular if it has a representative which is an immersion at  $0 \in \mathbb{R}^n$ . The manifold  $T_n^r Y$  of  $(r, n)$ -velocities as well as its open,  $L_n^r$ -invariant, dense submanifold  $\text{Imm } T_n^r Y$  of regular  $(r, n)$ -velocities, are endowed with a natural action of the differential group  $L_n^r$  of invertible  $r$ -jets with source and target  $0 \in \mathbb{R}^n$ . In this paper, we describe all continuous,  $L_n^r$ -invariant, real-valued functions on  $T_n^r Y$  and  $\text{Imm } T_n^r Y$ . We find local bases of  $L_n^r$ -invariants  $\text{Imm } T_n^r Y$  in an explicit, recurrent form. To this purpose, higher-order Grassmann bundles are considered as the corresponding quotients  $P_n^r Y = \text{Imm } T_n^r Y / L_n^r$ , and their basic properties are studied. We show that nontrivial  $L_n^r$ -invariants on  $\text{Imm } T_n^r Y$  cannot be continuously extended onto  $T_n^r Y$ .

*Subj. Class.:* Differential invariants; Grassmann bundles

*1991 MSC:* 53A55, 77S25, 58A20

*Keywords:* Jet of a mapping; Immersion; Contact element; Differential group; Grassmann bundle; Differential invariant

---

## 1. Introduction

By a *velocity* one usually means the derivative of a curve in a smooth manifold  $Y$  at a point, or, which is the same, the tangent vector to this curve at a point  $y \in Y$ . Equivalently,

---

<sup>\*</sup> Research of the first author supported by Grant No. 871/95 of the Ministry of Education and Youth of the Czech Republic. Research of the second author supported by Grant No. 201/96/0845 of the Czech Grant Agency.

<sup>\*</sup> Corresponding author. E-mail: demeter.krupka@fpf.slu.cz.

<sup>1</sup> Permanent address: Department of Theoretical Physics, Institute of Atomic Physics, Bucharest-Măgurele, PO Box MG6, România. E-mail: grigoretheor1.ifa.ro, grigoroifa.ifa.ro.

such a velocity is a 1-jet with *source* at the origin  $0 \in \mathbb{R}$  and *target* in  $Y$ . Generalizing this concept one may define an  $(r, n)$ -velocity as an  $r$ -jet with source  $0 \in \mathbb{R}^n$  and target in  $Y$ . If such an  $r$ -jet can be represented by an immersion of a neighborhood of the origin  $0 \in \mathbb{R}^n$  into  $Y$ , it is called *regular*, and we speak of a *regular*  $(r, n)$ -velocity.

Concepts of this kind, i.e., the  $r$ -jets of differentiable mappings between smooth manifolds, the contact elements or, which is the same,  $r$ -jets of submanifolds, have been introduced in the fiftieth by Ehresmann (see references in [7]), and have become the basic concepts of the theory of differential invariants, and the theory of natural bundles and operators (see [7,10,13,14] and the references there in). These concepts have also been applied in global analysis, and mathematical physics. It should be pointed out, however, that the problem of finding invariants of velocities and the corresponding problem of describing the structure of the space of higher-order velocities has not been touched in the existing monographs on differential invariants and natural bundles [7,13].

The set  $T_n^r Y$  of  $(r, n)$ -velocities on a smooth manifold is a smooth manifold endowed with a right action of the differential group  $L_n^r$  of invertible  $r$ -jets with source and target  $0 \in \mathbb{R}^n$ . The purpose of this paper is to characterize all continuous scalar invariants of this action, i.e. all real-valued functions defined on open subsets of  $T_n^r Y$ , which are constants on the  $L_n^r$ -orbits. Instead of formulating and solving equations for invariant functions we use a different, more powerful method based on considering the quotient space of the open, dense subspace of  $T_n^r Y$ , formed by regular  $(r, n)$ -velocities. The corresponding orbit space is then called the  $(r, n)$ -Grassmann bundle. It is a fiber bundle over  $Y$  whose type fiber is the  $(r, n)$ -Grassmannian. The canonical quotient projection of the manifold of regular  $(r, n)$ -velocities onto the orbit space is the *basis of invariants* of  $(r, n)$ -velocities. Geometric structures of this kind as well as their invariants have been studied by M. Krupka [11,12].

Thus, to find all  $L_n^r$ -invariants it is enough to find the projection of the manifolds of regular higher-order velocities onto the higher-order Grassmann bundle. We note that an analogous method has been applied to the problem of finding  $GL_n(\mathbb{R})$ -invariants of a linear connection [9].

Basic concepts of the *first-order* Grassmann bundles has been applied in mathematical physics, and the parametrization independent variational theory (see e.g. [1,3–6]). *Higher-order* Grassmann bundles have become natural underlying structures for the geometric theory of partial differential equations [8].

## 2. Higher-order velocities

Throughout this paper,  $m, n \geq 1$  and  $r \geq 0$  are integers such that  $n \leq m$ , and  $Y$  is a smooth manifold of dimension  $n + m$ .

By an  $(r, n)$ -velocity at a point  $y \in Y$  we mean an  $r$ -jet  $J_0^r \zeta$  with *source*  $0 \in \mathbb{R}^n$  and *target*  $y = \zeta(0)$ . The set of  $(r, n)$ -velocities at  $y$  is denoted by  $J_{(0,y)}^r(\mathbb{R}^n, Y)$ . Further, we denote

$$T_n^r Y = \bigcup_{y \in Y} J_{(0,y)}^r(\mathbb{R}^n, Y).$$

and define surjective mappings  $\tau_n^{r,s} : T_n^r Y \rightarrow T_n^s Y$ , where  $0 \leq s \leq r$ , by  $\tau_n^{r,s}(J_0^r \zeta) = J_0^s \zeta$ . Recall that the set  $T_n^r Y$  has a smooth structure defined as follows. Let  $(V, \psi)$ ,  $\psi = (y^A)$ , be a chart on  $Y$ . Then the associated chart  $(V_n^r, \psi_n^r)$  on  $T_n^r Y$  is defined by  $V_n^r = (\tau_n^{r,0})^{-1}(V)$ ,  $\psi_n^r = (y^A, y_{i_1}^A, y_{i_1 i_2}^A, \dots, y_{i_1 i_2 \dots i_r}^A)$ , where  $1 \leq i_1 \leq i_2 \leq \dots \leq i_r \leq n$ , and for every  $J_0^r \zeta \in V_n^r$ ,

$$y_{i_1 i_2 \dots i_k}^A(J_0^r \zeta) = D_{i_1} D_{i_2} \dots D_{i_k}(y^A \zeta)(0), \quad 0 \leq k \leq r. \tag{2.1}$$

The set  $T_n^r Y$  endowed with the smooth structure defined by the associated charts is called the manifold of  $(r, n)$ -velocities over  $Y$ .

The equations of the mapping  $\tau_n^{r,s} : T_n^r Y \rightarrow T_n^s Y$  in terms of the associated charts are given by  $y_{i_1 i_2 \dots i_k}^A \circ \tau_n^{r,s}(J_0^r \zeta) = y_{i_1 i_2 \dots i_k}^A(J_0^s \zeta)$ , where  $0 \leq k \leq s$ . In particular, these mappings are all submersions.

Let  $\text{tr}_t$  denote the translation  $t' \rightarrow t' + t$  of  $\mathbb{R}^n$ . If  $\gamma$  is a smooth mapping of an open set  $U \subset \mathbb{R}^n$  into  $Y$ , then for any  $t \in U$ , the mapping  $t' \rightarrow \gamma \circ \text{tr}_t(t')$  is defined on a neighborhood of the origin  $0 \in \mathbb{R}^n$  so that the  $r$ -jet  $J_0^r(\gamma \circ \text{tr}_t)$  is defined. The mapping

$$U \ni t \rightarrow (T_n^r \gamma)(t) = J_0^r(\gamma \circ \text{tr}_t) \in T_n^r Y \tag{2.2}$$

is called the  $r$ -prolongation, or simply the prolongation of  $\gamma$ . Since  $y_{i_1 i_2 \dots i_k}^A \circ T_n^r \gamma(t) = D_{i_1} D_{i_2} \dots D_{i_k}(y^A(\gamma \circ \text{tr}_t))(0)$  and  $D_{i_1}(y^A(\gamma \circ \text{tr}_t))(t') = D_{i_1}(y^A \gamma)(t' + t)$ , we get for its chart expression

$$y_{i_1 i_2 \dots i_k}^A \circ T_n^r \gamma(t) = D_{i_1} D_{i_2} \dots D_{i_k}(y^A \gamma)(t). \tag{2.3}$$

Assume that we have an element  $J_0^r \zeta \in T_n^r Y$ .  $J_0^r \zeta$  defines the tangent mapping  $T_0 T_n^{r-1} \zeta$ , which sends a tangent vector  $\xi \in T_0 \mathbb{R}^n$  to the tangent vector  $T_0 T_n^{r-1} \zeta \cdot \xi$  to  $T_n^{r-1} Y$  at  $J_0^{r-1} \zeta$ . If  $\xi = \xi^i (\partial/\partial t^i)_0$ , then by (2.3),

$$\begin{aligned} T_0 T_n^{r-1} \zeta \cdot \xi &= \sum_{k=0}^{r-1} \sum_{i_1 \leq i_2 \leq \dots \leq i_k} \left( \frac{\partial (y_{i_1 i_2 \dots i_k}^A \circ T_n^{r-1} \zeta)}{\partial t^i} \right)_0 \xi^i \left( \frac{\partial}{\partial y_{i_1 i_2 \dots i_k}^A} \right)_{J_0^{r-1} \zeta} \\ &= \sum_{k=0}^{r-1} \sum_{i_1 \leq i_2 \leq \dots \leq i_k} y_{i_1 i_2 \dots i_k}^A(J_0^r \zeta) \xi^i \left( \frac{\partial}{\partial y_{i_1 i_2 \dots i_k}^A} \right)_{J_0^{r-1} \zeta} \\ &= \xi^i d_i(J_0^r \zeta), \end{aligned} \tag{2.4}$$

where

$$d_i = \sum_{k=0}^{r-1} \sum_{i_1 \leq i_2 \leq \dots \leq i_k} y_{i_1 i_2 \dots i_k}^A \frac{\partial}{\partial y_{i_1 i_2 \dots i_k}^A} \tag{2.5}$$

is a morphism  $T_n^r Y \ni J_0^r \zeta \rightarrow d_i(J_0^r \zeta) \in T T_n^{r-1} Y$  over  $T_n^{r-1} Y$ . Indeed, the tangent vectors  $d_i(J_0^r \zeta)$  are defined independently of the chosen chart: If  $(\bar{V}, \bar{\psi})$ ,  $\bar{\psi} = (\bar{y}^A)$ , is some other chart at  $\zeta(0)$ , then

$$\bar{d}_i = \sum_{k=0}^r \sum_{j_1 \leq j_2 \leq \dots \leq j_k} \bar{y}_{j_1 j_2 \dots j_k}^A \frac{\partial}{\partial \bar{y}_{j_1 j_2 \dots j_k}^A},$$

and by (2.4),

$$\bar{d}_i = d_i. \tag{2.6}$$

We note that formula (2.5) does not define a vector field on  $T_n^r Y$  since it is not invariant when the tangent vectors  $\partial/\partial y_{i_1 i_2 \dots i_k}^\sigma$  are subject to coordinate transformations on  $T_n^r Y$ .

Let  $f : V_n^{r-1} \rightarrow \mathbb{R}$  be a smooth function. We define the  $i$ th formal derivative  $d_i f : V_n^r \rightarrow \mathbb{R}$  by

$$d_i f = \sum_{k=0}^{r-1} \sum_{j_1 \leq j_2 \leq \dots \leq j_k} y_{j_1 j_2 \dots j_k}^A \frac{\partial f}{\partial y_{j_1 j_2 \dots j_k}^A}.$$

By (2.6), the functions  $d_i f$  are independent of the charts, and the definition of the  $i$ th formal derivative is naturally extended to functions defined on an arbitrary open subset of  $T_n^{r-1} Y$ .

It can be easily verified that for every smooth function  $f : V_n^{r-1} \rightarrow \mathbb{R}$  and every smooth mapping  $\gamma$  of an open set  $U \subset \mathbb{R}^n$  into  $Y$ ,  $d_i f \circ T_n^r \gamma = D_i (f \circ T_n^{r-1} \gamma)$ . In particular, we have for every coordinate function  $y_{j_1 j_2 \dots j_k}^A$ ,

$$d_i y_{j_1 j_2 \dots j_k}^A = y_{j_1 j_2 \dots j_{k+1}}^A. \tag{2.7}$$

Using the formal derivative operators  $d_i$ , it is now very easy to find the transformation formulas between two associated charts on  $T_n^r Y$ . By (2.7) and (2.6),

$$\bar{y}_{j_1 j_2 \dots j_k j_{k+1}}^A = \bar{d}_{j_{k+1}} \bar{y}_{j_1 j_2 \dots j_k}^A = d_{j_{k+1}} y_{j_1 j_2 \dots j_k}^A = \dots = d_{j_{k+1}} \dots d_{j_2} d_{j_1} \bar{y}^A.$$

This formula may be applied whenever the transformation rules for the coordinate transformations on  $Y$  are known.

We shall need a formula for higher-order partial derivatives of the composed mapping in a form well adapted to its use in various inductive calculations in the higher-order differential geometry and the theory of differential invariants.

Let  $n$  and  $k$  be integers. If  $I = \{i_1, i_2, \dots, i_k\}$  is a set of indices such that  $1 \leq i_1, i_2, \dots, i_k \leq n$ , we usually denote  $D_I = D_{i_k} \dots D_{i_2} D_{i_1}$ . Let  $U$  and  $V$  be open subsets of  $\mathbb{R}^n$ , let  $f : V \rightarrow \mathbb{R}$  be a smooth function, and let  $\alpha = (\alpha^i)$  be a smooth mapping of  $U$  into  $V$ . Then one can prove by induction that

$$\begin{aligned} & D_{i_1} \dots D_{i_2} D_{i_1} (f \circ \alpha)(t) \\ &= \sum_{k=1}^s \sum_{I=(I_1, I_2, \dots, I_k)} D_{p_k} \dots D_{p_2} D_{p_1} f(\alpha(t)) D_{I_k} \alpha^{p_k}(t) \dots D_{I_2} \alpha^{p_2}(t) D_{I_1} \alpha^{p_1}(t), \end{aligned} \tag{2.8}$$

where the second sum is understood to be extended to all partitions  $(I_1, I_2, \dots, I_k)$  of the set  $\{i_1, i_2, \dots, i_s\}$ .

Let us write the transformation equations from  $(V, \psi)$  to  $(\bar{V}, \bar{\psi})$  in the form

$$\bar{y}^A = F^A(y^B). \tag{2.9}$$

We wish to determine explicitly the functions  $F_{i_1}^A, F_{i_1 i_2}^A, \dots, F_{i_1 i_2 \dots i_r}^A$ , defining the corresponding transformation

$$\bar{y}_{i_1 i_2 \dots i_k}^A = F_{i_1 i_2 \dots i_k}^A(y^{B_1}, y_{j_1}^{B_1}, y_{j_1 j_2}^{B_2}, \dots, y_{j_1 j_2 \dots j_k}^{B_k}), \quad 0 \leq k \leq r \tag{2.10}$$

from  $(V_n^r, \psi_n^r)$  to  $(\bar{V}_n^r, \bar{\psi}_n^r)$ .

**Lemma 1.** *The following formula holds:*

$$F_{i_1 i_2 \dots i_s}^A = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} y_{I_1}^{B_1} y_{I_2}^{B_2} \dots y_{I_p}^{B_p} \frac{\partial^p F^A}{\partial y^{B_1} \partial y^{B_2} \dots \partial y^{B_p}}, \tag{2.11}$$

where the second sum denotes summation over all partitions  $(I_1, I_2, \dots, I_p)$  of the set  $\{i_1, i_2, \dots, i_s\}$ .

*Proof.* We proceed by induction using (2.7). □

We assume that the reader is familiar with the concept of the differential group. Recall that the  $r$ -th differential group of  $\mathbb{R}^n$ , denoted by  $L_n^r$ , is the Lie group of invertible  $r$ -jets with source and target at  $0 \in \mathbb{R}^n$ . The group multiplication in  $L_n^r$  is defined by the jet composition

$$L_n^r \times L_n^r \ni (J_0^r \alpha, J_0^r \beta) \rightarrow J_0^r \alpha \circ J_0^r \beta = J_0^r (\alpha \circ \beta) \in L_n^r, \tag{2.12}$$

where  $\circ$  denotes both the composition of mappings, and the composition of  $r$ -jets. The canonical (global) coordinates on  $L_n^r$  are defined by

$$a_{i_1 i_2 \dots i_k}^j (J_0^r \alpha) = D_{i_1} D_{i_2} \dots D_{i_k} \alpha^j (0), \quad 1 \leq k \leq r, \quad 1 \leq i_1 \leq i_2 \leq \dots \leq i_k \leq n, \tag{2.13}$$

where  $\alpha^j$  are the components of a representative  $\alpha$  of  $J_0^r \alpha$ .

**Lemma 2.** *The group multiplication (2.12) in  $L_n^r$  is expressed in the canonical coordinates (2.13) by the equations*

$$c_{i_1 i_2 \dots i_s}^k = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} b_{I_1}^{j_1} b_{I_2}^{j_2} \dots b_{I_p}^{j_p} a_{j_1 j_2 \dots j_p}^k, \tag{2.14}$$

where  $a_{i_1 i_2 \dots i_s}^k = a_{i_1 i_2 \dots i_s}^k (J_0^r \alpha)$ ,  $b_{i_1 i_2 \dots i_s}^k = a_{i_1 i_2 \dots i_s}^k (J_0^r \beta)$ ,  $c_{i_1 i_2 \dots i_s}^k = a_{i_1 i_2 \dots i_s}^k (J_0^r (\alpha \circ \beta))$ , and the second sum is extended to all partitions  $(I_1, I_2, \dots, I_p)$  of the set  $\{i_1, i_2, \dots, i_s\}$ .

*Proof.* We apply (2.8). □

The manifolds of  $(r, n)$ -velocities  $T_n^r Y$  is endowed with a smooth right action of the differential group  $L_n^r$ , defined by the jet composition

$$T_n^r Y \times L_n^r \ni (J_0^r \zeta, J_0^r \alpha) \rightarrow J_0^r \zeta \circ J_0^r \alpha = J_0^r (\zeta \circ \alpha) \in T_n^r Y. \tag{2.15}$$

Let us determine the chart expression of this action. To this purpose we use the canonical coordinates  $a_I^i$  (2.13) on  $L_n^r$ .

**Lemma 3.** *The group action (2.15) is expressed by the equations*

$$\bar{y}^A = y^A, \quad \bar{y}_{i_1 i_2 \dots i_s}^A = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^A, \quad (2.16)$$

where the second sum is extended to all partitions  $(I_1, I_2, \dots, I_p)$  of the set  $\{i_1, i_2, \dots, i_s\}$ .

*Proof.* To prove (2.16), we apply (2.1), (2.15) and (2.8). □

Note the following formula. If  $\gamma$  is a smooth mapping of an open set  $U \subset \mathbb{R}^n$  into  $Y$ ,  $U' \subset \mathbb{R}^n$  an open set, and  $\alpha : U' \rightarrow U$  a smooth mapping, then for every  $t \in U'$ ,

$$T_n^r(\gamma \circ \alpha)(t) = (T_n^r \gamma)(\alpha(t)) \circ J_0^r(\text{tr}_{-\alpha(t)} \circ \alpha \circ \text{tr}_t). \quad (2.17)$$

To derive this formula, we use definition (2.2), and the identity  $J_0^r(\gamma \circ \alpha \circ \text{tr}_t) = J_0^r(\gamma \circ \text{tr}_{\alpha(t)}) \circ J_0^r(\text{tr}_{-\alpha(t)} \circ \alpha \circ \text{tr}_t)$ . In particular, if  $\alpha$  is a diffeomorphism, then  $J_0^r(\text{tr}_{-\alpha(t)} \circ \alpha \circ \text{tr}_t) \in L_n^r$ , and (2.17) reduces to the group action (2.15).

### 3. Higher-order Grassmann bundles

An  $(r, n)$ -velocity  $J_0^r \zeta \in T_n^r Y$  is said to be *regular* if it has a representative which is an immersion. If  $(V, \psi)$ ,  $\psi = (y^A)$ , is a chart, and the target  $\zeta(0)$  of an element  $J_0^r \zeta \in T_n^r Y$  belongs to  $V$ , then  $J_0^r \zeta$  is regular if and only if there exists a subsequence  $\nu = (\nu_1, \nu_2, \dots, \nu_n)$  of the sequence  $(1, 2, \dots, n, n + 1, \dots, n + m)$  such that  $\det D_i(y^{\nu_k} \circ \zeta)(0) \neq 0$ . Regular  $(r, n)$ -velocities form an open,  $L_n^r$ -invariant subset of  $T_n^r Y$ , which is called the *manifold of regular  $(r, n)$ -velocities*, and is denoted by  $\text{Imm } T_n^r Y$ . Recall that  $\text{Imm } T_n^r Y$  is endowed with a smooth right action of the differential group  $L_n^r$ , defined by restricting (2.15), i.e. by

$$\text{Imm } T_n^r Y \times L_n^r \ni (J_0^r \zeta, J_0^r \alpha) \rightarrow J_0^r \zeta \circ J_0^r \alpha = J_0^r(\zeta \circ \alpha) \in \text{Imm } T_n^r Y. \quad (3.1)$$

If  $a_{i_1}^k, a_{i_1 i_2}^k, \dots, a_{i_1 i_2 \dots i_r}^k$  are the canonical coordinates on  $L_n^r$ , this action is expressed by the equations

$$\bar{y}^A = y^A, \quad \bar{y}_{i_1 i_2 \dots i_s}^A = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^A. \quad (3.2)$$

In the proof of the following result we construct, among others, a complete system of  $L_n^r$ -invariants of the action (3.1) on  $\text{Imm } T_n^r Y$ . We use the *associated charts* on  $\text{Imm } T_n^r Y$ , which are defined as intersections of  $\text{Imm } T_n^r Y$  with associated charts on  $T_n^r Y$ .

**Theorem 1.** *The group action (3.1) defines on  $\text{Imm } T_n^r Y$  the structure of a right principal  $L_n^r$ -bundle.*

*Proof.* We have to show that (a) the equivalence  $\mathcal{R}$  “there exists  $J_0^r \alpha \in L_n^r$  such that  $J_0^r \zeta = J_0^r \chi \circ J_0^r \alpha$ ” is a closed submanifold of the product manifold  $\text{Imm } T_n^r Y \times \text{Imm } T_n^r Y$ , and (b) the group action (3.1) is free.

(a) First we construct an atlas on  $\text{Imm } T_n^r Y$ , adapted to the group action (3.1).

Let  $(V, \psi)$ ,  $\psi = (y^A)$ , be a chart on  $Y$ ,  $(V_n^r, \psi_n^r)$ ,  $\psi_n^r = (y^A, y_{j_1}^A, \dots, y_{j_1 j_2 \dots j_r}^A)$ , the associated chart on  $\text{Imm } T_n^r Y$ . We set for every subsequence  $\nu = (\nu_1, \nu_2, \dots, \nu_n)$  of the sequence  $(1, 2, \dots, n, n + 1, \dots, n + m)$

$$W^\nu = \{J_0^r \zeta \in V_n^r \mid \det(y_j^{\nu_k}(J_0^r \zeta)) \neq 0\}. \tag{3.3}$$

$W^\nu$  is an open,  $L_n^r$ -invariant subset of  $V_n^r$ , and

$$\bigcup_\nu W^\nu = V_n^r.$$

Restricting the mapping  $\psi_n^r$  to  $W^\nu$  we obtain a chart  $(W^\nu, \psi_n^r)$ .

The equivalence  $\mathcal{R}$  is obviously covered by the open sets of the form  $W^\nu \times W^\nu$ . We shall find its equations in terms of the charts  $(W^\nu \times W^\nu, \psi_n^r \times \psi_n^r)$ . Let us consider the set  $\mathcal{R} \cap (W^\nu \times W^\nu)$ . Assume for simplicity that  $\nu = (1, 2, \dots, n)$ . A point  $(J_0^r \zeta, J_0^r \chi) \in W^\nu \times W^\nu$  belongs to  $\mathcal{R} \cap (W^\nu \times W^\nu)$  if and only if there exists  $J_0^r \alpha \in L_n^r$  such that  $J_0^r \zeta = J_0^r \chi \circ J_0^r \alpha$  or, which is the same, if and only if the system of equations (3.2) has a solution  $a_{i_1}^k, a_{i_1 i_2}^k, \dots, a_{i_1 i_2 \dots i_r}^k$ . Clearly, in this system  $\bar{y}^A, \bar{y}_{i_1}^A, \bar{y}_{i_1 i_2}^A, \dots, \bar{y}_{i_1 i_2 \dots i_r}^A$  (resp.  $y^A, y_{p_1}^A, y_{p_1 p_2}^A, \dots, y_{p_1 p_2 \dots p_r}^A$ ) are coordinates of  $J_0^r \zeta$  (resp.  $J_0^r \chi$ ). But on  $W^\nu$ ,  $\det(y_i^k) \neq 0$ , where  $1 \leq i, k \leq n$ . Consequently, there exist functions  $z_j^i : W^\nu \rightarrow \mathbb{R}$  such that  $z_j^i y_i^k = \delta_j^k$ . Conditions (3.2) now imply, for  $A = k = 1, 2, \dots, n$ ,

$$\begin{aligned} \bar{y}_{i_1 i_2 \dots i_s}^k &= \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^k \\ &= \sum_{p=2}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^k + a_{i_1 i_2 \dots i_s}^{j_1} y_{j_1}^k, \end{aligned}$$

which allows us to determine the canonical coordinates of the group element  $J_0^r \alpha$  by the recurrent formula

$$a_{i_1 i_2 \dots i_s}^q = z_k^q \left( \bar{y}_{i_1 i_2 \dots i_s}^k - \sum_{p=2}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^k \right). \tag{3.4}$$

Taking  $A = \sigma = n + 1, n + 2, \dots, n + m$  in (3.2) and substituting from (3.4) we get

$$\bar{y}_{i_1 i_2 \dots i_s}^\sigma = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^\sigma, \tag{3.5}$$

where the group parameters  $a_j^i$  are all certain rational functions of  $y_{j_1 j_2 \dots j_s}^\lambda, \bar{y}_{j_1 j_2 \dots j_s}^\lambda$ . These are the desired equations of the equivalence  $\mathcal{R}$  on  $W^\nu \times W^\nu$ .

Now define a new chart on  $\text{Imm } T_n^r Y \times \text{Imm } T_n^r Y$ ,  $(W^v \times W^v, \Phi^v)$ , where  $\Phi^v = (y^A, y_{j_1}^A, y_{j_1 j_2}^A, \dots, y_{j_1 j_2 \dots j_r}^A, \Phi^\sigma, \Phi_{j_1}^\sigma, \Phi_{j_1 j_2}^\sigma, \dots, \Phi_{j_1 j_2 \dots j_r}^\sigma, \bar{y}^k, \bar{y}_{j_1}^k, \bar{y}_{j_1 j_2}^k, \dots, \bar{y}_{j_1 j_2 \dots j_r}^k)$  is the collection of coordinate functions, by

$$\Phi^\sigma = \bar{y}^\sigma - y^\sigma, \quad \Phi_{i_1 i_2 \dots i_s}^\sigma = \bar{y}_{i_1 i_2 \dots i_s}^\sigma - \sum_{p=1}^s \sum_{(l_1, l_2, \dots, l_p)} a_{l_1}^{j_1} a_{l_2}^{j_2} \dots a_{l_p}^{j_p} y_{j_1 j_2 \dots j_p}^\sigma.$$

In terms of this new chart, the equivalence  $\mathcal{R}$  has equations  $\Phi^\sigma = 0, \Phi_{i_1 i_2 \dots i_s}^\sigma = 0$ , and is therefore a closed submanifold of  $\text{Imm } T_n^r Y \times \text{Imm } T_n^r Y$ .

(b) Assume that for some  $J_0^r \zeta \in \text{Imm } T_n^r Y$  and  $J_0^r \alpha \in L_n^r, J_0^r \zeta \circ J_0^r \alpha = J_0^r \zeta$ . Then Eqs. (3.2) reduce to

$$y_{i_1 i_2 \dots i_s}^A = \sum_{p=1}^s \sum_{(l_1, l_2, \dots, l_p)} a_{l_1}^{j_1} a_{l_2}^{j_2} \dots a_{l_p}^{j_p} y_{j_1 j_2 \dots j_p}^A,$$

which gives us, using (3.4),  $a_i^p = \delta_i^p, a_{i_1 i_2}^p = 0, \dots, a_{i_1 i_2 \dots i_r}^p = 0$ , i.e.,  $J_0^r \alpha = J_0^r \text{id}_{\mathbb{R}^v}$ .

This completes the proof. □

We have the following corollaries.

**Corollary 1.** *The orbit space  $P_n^r Y = \text{Imm } T_n^r Y / L_n^r$  has a unique smooth structure such that the canonical quotient projection  $\rho_n^r : \text{Imm } T_n^r Y \rightarrow P_n^r Y$  is a submersion. The dimension of  $P_n^r Y$  is*

$$\dim P_n^r Y = m \binom{n+r}{n} + n.$$

The following corollary solves the problem of finding all  $L_n^r$ -invariant functions on  $\text{Imm } T_n^r Y$ . It says that the projection  $\rho_n^r : \text{Imm } T_n^r Y \rightarrow P_n^r Y$  is the basis of  $L_n^r$ -invariant functions.

**Corollary 2.** *Every  $L_n^r$ -invariant function  $f : W \rightarrow \mathbb{R}$ , where  $W \subset \text{Imm } T_n^r Y$  is an  $L_n^r$ -invariant open set, can be factored through the projection mapping  $\rho_n^r : \text{Imm } T_n^r Y \rightarrow P_n^r Y$ .*

Now we are going to construct charts on  $\text{Imm } T_n^r Y$  adapted to the right action (3.1) of the differential group  $L_n^r$ . We may consider, for example, the charts (3.3) with  $v = (1, 2, \dots, n)$ .

**Theorem 2.** *Let  $(V, \psi), \psi = (y^A)$ , be a chart on  $Y, (V_n^r, \psi_n^r), \psi_n^r = (y_{i_1 i_2 \dots i_s}^A), s \leq r$ , the associated chart on  $\text{Imm } T_n^r Y$ , and  $W = \{J_0^r \zeta \in V_n^r \mid \det(y_j^i(J_0^r \zeta)) \neq 0\}, 1 \leq i, j \leq n$ . There exist unique functions  $w^\sigma, w_{j_1}^\sigma, w_{j_1 j_2}^\sigma, \dots, w_{j_1 j_2 \dots j_r}^\sigma$  defined on  $W$  such that*

$$y^\sigma = w^\sigma, \quad y_{p_1 p_2 \dots p_k}^\sigma = \sum_{q=1}^k \sum_{(l_1, l_2, \dots, l_q)} y_{l_1}^{j_1} y_{l_2}^{j_2} \dots y_{l_q}^{j_q} w_{j_1 j_2 \dots j_q}^\sigma. \tag{3.6}$$



The pair  $(W, \Phi)$ , where  $\Phi = (w^\sigma, w_{p_1}^\sigma, w_{p_1 p_2}^\sigma, \dots, w_{p_1 p_2 \dots p_r}^\sigma, y^i, y_{j_1}^i, y_{j_1 j_2}^i, \dots, y_{j_1 j_2 \dots j_r}^i)$ , is a chart on  $\text{Imm } T_n^r Y$ . The functions  $w^\sigma, w_{j_1}^\sigma, w_{j_1 j_2}^\sigma, \dots, w_{j_1 j_2 \dots j_r}^\sigma$  satisfy the recurrent formula

$$w_{j_1 j_2 \dots j_k j_{k+1}}^\sigma = z_{j_{k+1}}^s d_s w_{j_1 j_2 \dots j_k}^\sigma, \tag{3.7}$$

and are  $L_n^r$ -invariant.

*Proof.* We proceed by induction.

(1) We prove that the assertion is true for  $r = 1$ . Consider the pair  $(W, \Phi)$ ,  $\Phi = (w^\sigma, w_{p_1}^\sigma, y^i, y_{j_1}^i)$ , where  $w^\sigma = y^\sigma, w_j^\sigma = z_j^k y_k^\sigma$ . Obviously  $y_p^\sigma = y_p^j w_j^\sigma$ , which implies that  $(W, \Phi)$  is a new chart. Moreover,  $w_j^\sigma = z_j^k d_k y^\sigma = z_j^k d_k w^\sigma$ . It remains to show that the functions  $w_j^\sigma$  are  $L_n^1$ -invariant. Since the group action (3.2) is expressed by  $\bar{y}^i = y^i, \bar{y}^\sigma = y^\sigma, \bar{y}_p^i = a_p^j y_j^i, \bar{y}_p^\sigma = a_p^j y_j^\sigma$ , the inverse of the matrix  $\bar{y}_p^i = a_p^j y_j^i$  is  $\bar{z}_q^p = z_q^p b_s^p$ , where  $b_s^p$  stands for the inverse of  $a_s^p$ . Hence  $\bar{w}_j^\sigma = \bar{z}_j^k \bar{y}_k^\sigma = z_j^s b_s^k a_k^p y_p^\sigma = z_j^p y_p^\sigma = w_j^\sigma$  proving the invariance.

(2) Assume that formulas (3.6), (3.7) hold for  $k = r - 1$ . Write (3.6) in the form

$$y_{p_1 p_2 \dots p_k}^\sigma = \sum_{q=1}^k \sum_{(I_1, I_2, \dots, I_q)} y_{I_1}^{j_1} y_{I_2}^{j_2} \dots y_{I_q}^{j_q} w_{j_1 j_2 \dots j_q}^\sigma.$$

Then

$$\begin{aligned} y_{p_1 p_2 \dots p_k p_{k+1}}^\sigma &= d_{p_{k+1}} y_{p_1 p_2 \dots p_k}^\sigma \\ &= \sum_{q=1}^k \sum_{(I_1, I_2, \dots, I_q)} (d_{p_{k+1}} (y_{I_1}^{j_1} y_{I_2}^{j_2} \dots y_{I_q}^{j_q}) w_{j_1 j_2 \dots j_q}^\sigma \\ &\quad + y_{I_1}^{j_1} y_{I_2}^{j_2} \dots y_{I_q}^{j_q} y_{p_{k+1} z_{j_{q+1}}^s} d_s w_{j_1 j_2 \dots j_q}^\sigma). \end{aligned}$$

In this formula we sum through all partitions  $(I_1, I_2, \dots, I_q)$  of the set  $\{p_1, p_2, \dots, p_k\}$ . On the other hand, when passing to all partitions  $(J_1, J_2, \dots, J_q)$  of the set  $\{p_1, p_2, \dots, p_k, p_{k+1}\}$  we get

$$\begin{aligned} &y_{p_1 p_2 \dots p_k p_{k+1}}^\sigma \\ &= \sum_{q=1}^k \sum_{(I_1, I_2, \dots, I_q)} (d_{p_{k+1}} (y_{I_1}^{j_1} y_{I_2}^{j_2} \dots y_{I_q}^{j_q}) w_{j_1 j_2 \dots j_q}^\sigma \\ &\quad + y_{I_1}^{j_1} y_{I_2}^{j_2} \dots y_{I_q}^{j_q} y_{p_{k+1} z_{j_{q+1}}^s} d_s w_{j_1 j_2 \dots j_q}^\sigma) \\ &= \sum_{q=1}^k \sum_{(J_1, J_2, \dots, J_q)} y_{J_1}^{j_1} y_{J_2}^{j_2} \dots y_{J_q}^{j_q} w_{j_1 j_2 \dots j_q}^\sigma + y_{p_1}^{j_1} y_{p_2}^{j_2} \dots y_{p_q}^{j_q} y_{p_{k+1} z_{j_{q+1}}^s} d_s w_{j_1 j_2 \dots j_q}^\sigma, \end{aligned} \tag{3.8}$$

and we see that (3.8) has the same form as (3.6), where  $w_{j_1 j_2 \dots j_k j_{k+1}}^\sigma = z_{j_{k+1}}^s d_s w_{j_1 j_2 \dots j_k}^\sigma$ . Uniqueness is immediate since  $w_{j_1 j_2 \dots j_k j_{k+1}}^\sigma$  may be expressed explicitly from (3.8).

It remains to prove the invariance condition  $\bar{w}_{j_1 j_2 \dots j_s}^\sigma = w_{j_1 j_2 \dots j_s}^\sigma$ .

Since the points  $J_0^r \zeta \circ J_0^r \alpha$  and  $J_0^r \zeta$  belong to the same orbit, their coordinates satisfy the recurrence formula (3.5):

$$\bar{y}_{i_1 i_2 \dots i_s}^\sigma = \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^\sigma, \quad s = 1, 2, \dots, r.$$

in which

$$a_{k_1 k_2 \dots k_t}^q = z_k^q \left( \bar{y}_{i_1 i_2 \dots i_t}^k - \sum_{p=2}^t \sum_{(K_1, K_2, \dots, K_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^k \right)$$

for all  $t \leq s$  (see (3.4)). Here  $(I_1, I_2, \dots, I_p)$  is a partition of the set  $\{i_1, i_2, \dots, i_s\}$  and  $(K_1, K_2, \dots, K_p)$  is a partition of the set  $\{k_1, k_2, \dots, k_t\}$ . Using (3.6) we can write

$$\begin{aligned} \bar{y}_{i_1 i_2 \dots i_s}^\sigma &= \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} \dots \bar{y}_{I_p}^{j_p} \bar{w}_{j_1 j_2 \dots j_p}^\sigma, \\ y_{j_1 j_2 \dots j_s}^\sigma &= \sum_{l=1}^p \sum_{(J_1, J_2, \dots, J_l)} y_{J_1}^{i_1} y_{J_2}^{i_2} \dots y_{J_l}^{i_l} w_{i_1 i_2 \dots i_l}^\sigma, \end{aligned}$$

where  $(I_1, I_2, \dots, I_p)$  is a partition of the set  $\{i_1, i_2, \dots, i_s\}$  and  $(J_1, J_2, \dots, J_l)$  is a partition of the set  $\{j_1, j_2, \dots, j_p\}$ . This gives us the equation

$$\begin{aligned} &\sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} \dots \bar{y}_{I_p}^{j_p} \bar{w}_{j_1 j_2 \dots j_p}^\sigma \\ &= \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} \left( \sum_{l=1}^p \sum_{(J_1, J_2, \dots, J_l)} y_{J_1}^{i_1} y_{J_2}^{i_2} \dots y_{J_l}^{i_l} w_{i_1 i_2 \dots i_l}^\sigma \right). \end{aligned} \tag{3.9}$$

Now we wish to determine the terms  $w_{i_1 i_2 \dots i_p}^\sigma$  on the right-hand side with fixed  $p$ . Changing the notation of the indices, we get the expression

$$\sum_{q=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_q}^{j_q} \left( \sum_{p=1}^q \sum_{(J_1, J_2, \dots, J_p)} y_{J_1}^{i_1} y_{J_2}^{i_2} \dots y_{J_p}^{i_p} w_{i_1 i_2 \dots i_p}^\sigma \right)$$

from which we see that  $w_{i_1 i_2 \dots i_p}^\sigma$  are contained in every summand with  $q \geq p$ . Thus, the required terms are given by

$$\left( \sum_{q=p}^s \sum_{(I_1, I_2, \dots, I_q)} \sum_{(J_1, J_2, \dots, J_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_q}^{j_q} y_{J_1}^{i_1} y_{J_2}^{i_2} \dots y_{J_p}^{i_p} \right) w_{i_1 i_2 \dots i_p}^\sigma.$$

In this formula  $(I_1, I_2, \dots, I_q)$  is a partition of the set  $\{i_1, i_2, \dots, i_s\}$ , and  $(J_1, J_2, \dots, J_p)$  is a partition of the set  $\{j_1, j_2, \dots, j_q\}$ .

Now we adopt the following notation. If  $I = (i_1, i_2, \dots, i_s)$  is a multi-index, then  $(I_1, I_2, \dots, I_p) \sim I$  means that  $(I_1, I_2, \dots, I_p)$  is a partition of the set  $\{i_1, i_2, \dots, i_s\}$ .

As before, let  $I = (i_1, i_2, \dots, i_s)$ , and let  $p$  be fixed. We wish to show that

$$\begin{aligned} & \left( \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} \dots \bar{y}_{I_p}^{j_p} \right) w_{j_1 j_2 \dots j_p}^\sigma \\ &= \left( \sum_{q=1}^s \sum_{(I_1, I_2, \dots, I_q)} \sum_{(J_1, J_2, \dots, J_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_q}^{j_q} y_{J_1}^{t_1} y_{J_2}^{t_2} \dots y_{J_p}^{t_p} \right) w_{t_1 t_2 \dots t_p}^\sigma. \end{aligned} \tag{3.10}$$

Write the transformation formula (2.16) in the form

$$\bar{y}_I^A = \sum_{p=1}^{|I|} \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^A, \quad (I_1, I_2, \dots, I_p) \sim I.$$

Using the same notation, we have

$$\begin{aligned} \bar{y}_{I_k}^{t_k} &= \sum_{q_k=1}^{|I_k|} \sum_{(I_{k,1}, I_{k,2}, \dots, I_{k,q_k})} a_{I_{k,1}}^{j_{k,1}} a_{I_{k,2}}^{j_{k,2}} \dots a_{I_{k,q_k}}^{j_{k,q_k}} y_{j_{k,1} j_{k,2} \dots j_{k,q_k}}^{t_k}, \\ & \quad (I_{k,1}, I_{k,2}, \dots, I_{k,q_k}) \sim I_k, \end{aligned}$$

where  $(I_1, I_2, \dots, I_p) \sim I$ . Thus,

$$\begin{aligned} & \left( \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{t_1} \bar{y}_{I_2}^{t_2} \dots \bar{y}_{I_p}^{t_p} \right) w_{t_1 t_2 \dots t_p}^\sigma \\ &= \left( \sum_{q_1=1}^{|I_1|} \sum_{(I_{1,1}, I_{1,2}, \dots, I_{1,q_1})} a_{I_{1,1}}^{j_{1,1}} a_{I_{1,2}}^{j_{1,2}} \dots a_{I_{1,q_1}}^{j_{1,q_1}} y_{j_{1,1}}^{t_1} \right) \\ & \quad \times \left( \sum_{q_2=1}^{|I_2|} \sum_{(I_{2,1}, I_{2,2}, \dots, I_{2,q_2})} a_{I_{2,1}}^{j_{2,1}} a_{I_{2,2}}^{j_{2,2}} \dots a_{I_{2,q_2}}^{j_{2,q_2}} y_{j_{2,1}}^{t_2} \right) \\ & \quad \times \dots \left( \sum_{q_p=1}^{|I_p|} \sum_{(I_{p,1}, I_{p,2}, \dots, I_{p,q_p})} a_{I_{p,1}}^{j_{p,1}} a_{I_{p,2}}^{j_{p,2}} \dots a_{I_{p,q_p}}^{j_{p,q_p}} y_{j_{p,1}}^{t_p} \right) w_{t_1 t_2 \dots t_p}^\sigma, \end{aligned}$$

where  $J_1 = (j_{1,1}, j_{1,2}, \dots, j_{1,q_1})$ ,  $J_2 = (j_{2,1}, j_{2,2}, \dots, j_{2,q_2}), \dots$  and  $J_p = (j_{p,1}, j_{p,2}, \dots, j_{p,q_p})$ .

This expression can be written in a different way. Notice that since  $(I_{i,1}, I_{i,2}, \dots, I_{i,q_i}) \sim I_i$ , then

$$\begin{aligned} & (I_{1,1}, I_{1,2}, \dots, I_{1,q_1}, I_{2,1}, I_{2,2}, \dots, I_{2,q_2}, \dots, I_{p,1}, I_{p,2}, \dots, I_{p,q_p}) \sim I, \\ & |I_1| + |I_2| + \dots + |I_p| = |I| = s, \end{aligned}$$

and if we define  $q = q_1 + q_2 + \dots + q_p$ , we get  $p \leq q \leq |I_1| + |I_2| + \dots + |I_p| = |I| = s$ . Now, having in mind the corresponding summation ranges,

$$\begin{aligned} & \left( \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{I_1} \bar{y}_{I_2}^{I_2} \dots \bar{y}_{I_p}^{I_p} \right) w_{I_1 I_2 \dots I_p}^\sigma \\ &= \sum a_{I_{1,1}}^{j_{1,1}} a_{I_{1,2}}^{j_{1,2}} \dots a_{I_{1,q_1}}^{j_{1,q_1}} a_{I_{2,1}}^{j_{2,1}} a_{I_{2,2}}^{j_{2,2}} \dots a_{I_{2,q_2}}^{j_{2,q_2}} \dots a_{I_{p,1}}^{j_{p,1}} a_{I_{p,2}}^{j_{p,2}} \\ & \quad \times \dots a_{I_{p,q_p}}^{j_{p,q_p}} y_{J_1}^{I_1} y_{J_2}^{I_2} \dots y_{J_p}^{I_p} w_{I_1 I_2 \dots I_p}^\sigma. \end{aligned}$$

If we denote

$$\begin{aligned} & (s_1, s_2, \dots, s_q) \\ &= (j_{1,1}, j_{1,2}, \dots, j_{1,q_1}, j_{2,1}, j_{2,2}, \dots, j_{2,q_2}, \dots, j_{p,1}, j_{p,2}, \dots, j_{p,q_p}) \end{aligned}$$

and

$$\begin{aligned} & (P_1, P_2, \dots, P_q) \\ &= (I_{1,1}, I_{1,2}, \dots, I_{1,q_1}, I_{2,1}, I_{2,2}, \dots, I_{2,q_2}, \dots, I_{p,1}, I_{p,2}, \dots, I_{p,q_p}), \end{aligned}$$

it is immediate that  $(P_1, P_2, \dots, P_q) \sim I$ , and

$$\begin{aligned} & \left( \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{J_1} \bar{y}_{I_2}^{J_2} \dots \bar{y}_{I_p}^{J_p} \right) w_{J_1 J_2 \dots J_p}^\sigma \\ &= \left( \sum_{q=P}^s \sum_{(P_1, P_2, \dots, P_q)} \sum_{(J_1, J_2, \dots, J_p)} a_{P_1}^{s_1} a_{P_2}^{s_2} \dots a_{P_q}^{s_q} y_{J_1}^{I_1} y_{J_2}^{I_2} \dots y_{J_p}^{I_p} \right) w_{I_1 I_2 \dots I_p}^\sigma. \end{aligned}$$

This proves (3.10).

Returning to (3.9), and substituting from (3.10) we get a basic formula

$$\sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} \dots \bar{y}_{I_p}^{j_p} (\bar{w}_{j_1 j_2 \dots j_p}^\sigma - w_{j_1 j_2 \dots j_p}^\sigma) = 0. \tag{3.11}$$

Now it is easy to show that  $\bar{w}_{j_1 j_2 \dots j_s}^\sigma = w_{j_1 j_2 \dots j_s}^\sigma$  provided  $\bar{w}_{j_1 j_2 \dots j_k}^\sigma = w_{j_1 j_2 \dots j_k}^\sigma$  for all  $k \leq s - 1$ .

If  $s = 1$ , we get  $\bar{y}_{I_1}^{j_1} (\bar{w}_{j_1}^\sigma - w_{j_1}^\sigma) = 0$ , and since the matrix  $\bar{y}_i^j$  is regular,  $\bar{w}_j^\sigma = w_j^\sigma$ .

If  $s = 2$ , we have  $\bar{y}_{I_1 I_2}^{j_1} (\bar{w}_{j_1}^\sigma - w_{j_1}^\sigma) + \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} (\bar{w}_{j_1 j_2}^\sigma - w_{j_1 j_2}^\sigma) = \bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} (\bar{w}_{j_1 j_2}^\sigma - w_{j_1 j_2}^\sigma) = 0$ ,

which implies, again using regularity of the matrix  $\bar{y}_i^j$ , that  $\bar{w}_{j_1 j_2}^\sigma = w_{j_1 j_2}^\sigma$ .

Now assume that  $\bar{w}_{j_1 j_2 \dots j_k}^\sigma = w_{j_1 j_2 \dots j_k}^\sigma$  for all  $k \leq s - 1$ . Then (3.11) reduces to

$$\bar{y}_{I_1}^{j_1} \bar{y}_{I_2}^{j_2} \dots \bar{y}_{I_s}^{j_s} (\bar{w}_{j_1 j_2 \dots j_s}^\sigma - w_{j_1 j_2 \dots j_s}^\sigma) = 0,$$

which gives us  $\bar{w}_{j_1 j_2 \dots j_s}^\sigma - w_{j_1 j_2 \dots j_s}^\sigma = 0$  as required.

This completes the proof. □

Denote

$$\Delta_i = z_i^s d_s. \tag{3.12}$$

Properties of the group action of  $L_n^r$  on  $\text{Imm } T_n^r Y$  can now be summarized as follows.

**Corollary 3.** *The group action (3.1) is expressed on  $W$  by the equations*

$$\begin{aligned} \bar{y}^k &= y^k, & \bar{y}_{i_1 i_2 \dots i_s}^k &= \sum_{p=1}^s \sum_{(I_1, I_2, \dots, I_p)} a_{I_1}^{j_1} a_{I_2}^{j_2} \dots a_{I_p}^{j_p} y_{j_1 j_2 \dots j_p}^k, \\ \bar{w}_{j_1 j_2 \dots j_s}^\sigma &= w_{j_1 j_2 \dots j_s}^\sigma, & 0 \leq s \leq r. \end{aligned}$$

Equations  $w_{j_1 j_2 \dots j_s}^\sigma = c_{j_1 j_2 \dots j_s}^\sigma$ , where  $c_{j_1 j_2 \dots j_s}^\sigma \in \mathbb{R}$  are equations of the orbits of this action, and the functions  $y^i, w_{j_1 j_2 \dots j_s}^\sigma$  represent a complete system of real-valued  $L_n^r$ -invariants on  $W$ . Moreover, each of these invariants arises by applying a sequence of the vector fields  $\Delta_i$  to the invariants  $w^\sigma$ .

Our aim now will be to express the vector fields  $\Delta_i$  in terms of the adapted charts  $(W, \Phi)$  (Theorem 2).

**Corollary 4.** *The vector field  $\Delta_i$  has an expression*

$$\begin{aligned} \Delta_i(J_0^r \zeta) &= \frac{\partial}{\partial y^i} + \sum_{l=0}^{r-1} \sum_{p_1 \leq p_2 \leq \dots \leq p_l} w_{p_1 p_2 \dots p_l}^v(J_0^r \zeta) \left( \frac{\partial}{\partial w_{p_1 p_2 \dots p_l}^v} \right)_{J_0^r \zeta} \\ &+ \sum_{l=1}^{r-1} \sum_{p_1 \leq p_2 \leq \dots \leq p_l} z_i^s(J_0^r \zeta) y_{p_1 p_2 \dots p_l}^k(J_0^r \zeta) \left( \frac{\partial}{\partial y_{p_1 p_2 \dots p_l}^k} \right)_{J_0^r \zeta}. \end{aligned} \tag{3.13}$$

*Proof.* We proceed by direct computation, using (2.5) and Theorem 2. □

Note that at every point of its domain, the vector fields  $\Delta_i$  (3.12) span an  $n$ -dimensional vector subspace of the tangent space of  $\text{Imm } T_n^{r-1} Y$ , determined independently of charts. Indeed, if  $(V, \psi)$ , and  $(\bar{V}, \bar{\psi})$  are two charts, then by (2.6),

$$\bar{\Delta}_i = \bar{z}_i^s \bar{d}_s = \bar{z}_i^s d_s = \bar{z}_i^s \delta_s^p d_p = \bar{z}_i^s y_s^q z_q^p d_p = \bar{z}_i^s y_s^q \Delta_p. \tag{3.14}$$

In the following corollary we use these vector fields to derive the transformation properties of the functions  $w_{p_1 p_2 \dots p_k}^v$ . Denote  $P = (P_j^i)$ , where

$$P_j^i = \frac{\partial \bar{y}^i}{\partial y^j} + w_j^v \frac{\partial \bar{y}^i}{\partial w^v}.$$

Taking  $r = 1$  in (3.14), we get

$$\begin{aligned} \bar{\Delta}_i &= \frac{\partial}{\partial \bar{y}^i} + \bar{w}_i^v \frac{\partial}{\partial \bar{w}^v} = \bar{z}_i^s y_s^q \Delta_q \\ &= \bar{z}_i^s y_s^q \left( \frac{\partial \bar{y}^i}{\partial y^q} + w_j^v \frac{\partial \bar{y}^i}{\partial w^v} \right) \frac{\partial}{\partial \bar{y}^j} + \bar{z}_i^s y_s^q \left( \frac{\partial \bar{w}^v}{\partial y^q} + w_q^\lambda \frac{\partial \bar{w}^v}{\partial w^\lambda} \right) \frac{\partial}{\partial \bar{w}^v}, \end{aligned}$$

from which it follows that  $\delta_i^j = \bar{z}_i^s y_s^q P_i^j$ ,  $\bar{w}_i^v = \bar{z}_i^s y_s^q \Delta_q \bar{w}^v$ . The first of these conditions implies that the matrix  $P$  is regular, and its inverse,  $P^{-1} = Q = (Q_j^i)$ , satisfies

$$Q_j^i = \bar{z}_j^s y_s^i.$$

From the second condition we derive the following formula  $\bar{w}_i^v = Q_j^i \Delta_q \bar{w}^v$ .

**Corollary 5.** Let  $(V, \psi)$ ,  $\psi = (y^A)$  and  $(\bar{V}, \bar{\psi})$ ,  $\bar{\psi} = (\bar{y}^A)$  be two charts on  $Y$  such that  $V \cap \bar{V} \neq \emptyset$ . Consider the associated charts  $(V_n^r, \psi_n^r)$  and  $(\bar{V}_n^r, \bar{\psi}_n^r)$  and the charts  $(W, \Phi)$  and  $(\bar{W}, \bar{\Phi})$  on  $\text{Imm } T_n^r Y$ . Let the transformation equations from  $(V, \psi)$  to  $(\bar{V}, \bar{\psi})$  be written in the form

$$\bar{y}^i = F^i(y^k, w^v), \quad \bar{w}^\sigma = F^\sigma(y^k, w^v).$$

Then the functions  $w_{i_1 i_2 \dots i_k i_{k+1}}^v$  obey the transformation formulas

$$\bar{w}_{i_1 i_2 \dots i_k i_{k+1}}^v = Q_{i_{k+1}}^p \Delta_p \bar{w}_{i_1 i_2 \dots i_k}^v. \tag{3.15}$$

*Proof.* By hypothesis,  $\det(y_i^k) \neq 0$ , hence  $\det(\bar{y}_i^k) \neq 0$ . Therefore, using (3.7) we get  $\bar{w}_{i_1 i_2 \dots i_k i_{k+1}}^v = \bar{z}_{i_{k+1}}^s \delta_s^j d_j \bar{w}_{i_1 i_2 \dots i_k}^v = \bar{z}_{i_{k+1}}^s y_s^p z_p^j d_j \bar{w}_{i_1 i_2 \dots i_k}^v = Q_{i_{k+1}}^p \Delta_p \bar{w}_{i_1 i_2 \dots i_k}^v$ .  $\square$

A point of  $P_n^r Y$  containing a regular  $(r, n)$ -velocity  $J_0^r \zeta$  is called an  $(r, n)$ -contact element, or an  $r$ -contact element of an  $n$ -dimensional submanifold of  $Y$ , and is denoted by  $[J_0^r \zeta]$ . As in the case of  $r$ -jets, the point  $0 \in \mathbb{R}^n$  (resp.  $\zeta(0) \in Y$ ) is called the source (resp. the target) of  $[J_0^r \zeta]$ . The set  $G_n^r$  of  $(r, n)$ -contact elements with source  $0 \in \mathbb{R}^n$  and target  $0 \in \mathbb{R}^{n+m}$ , endowed with the natural smooth structure, is called the  $(r, n)$ -Grassmannian, or simply a higher-order Grassmannian. It is standard to check that the manifold  $P_n^r Y = \text{Imm } T_n^r Y / L_n^r$  is a fiber bundle over  $Y$  with fiber  $G_n^r$ .  $P_n^r Y$  with this structure is called the  $(r, n)$ -Grassmannian bundle, or simply a higher-order Grassmannian bundle over  $Y$ .

Besides the quotient projection  $\rho_n^r : \text{Imm } T_n^r Y \rightarrow P_n^r$  (Corollary 1) we have for every  $s, 0 \leq s \leq r$ , the canonical projection of  $P_n^r Y$  onto  $P_n^s Y$  defined by  $\rho_n^{r,s}([J_0^r \zeta]) = [J_0^s \zeta]$ .

Now we are going to introduce some charts on the manifold of contact elements  $P_n^r Y$ . To this purpose we consider the adapted charts on  $\text{Imm } T_n^r Y$ ,  $(W, \Phi)$ ,

$$\Phi = (w^\sigma, w_{p_1}^\sigma, w_{p_1 p_2}^\sigma, \dots, w_{p_1 p_2 \dots p_r}^\sigma, y^i, y_{j_1}^i, y_{j_1 j_2}^i, \dots, y_{j_1 j_2 \dots j_r}^i),$$

introduced in Theorem 2. We denote  $\tilde{W} = \rho_n^r(W)$ , and if  $J_n^r \zeta \in W$ , we define

$$\tilde{\Phi} = (\bar{y}^i, \bar{w}^\sigma, \bar{w}_{j_1}^\sigma, \bar{w}_{j_1 j_2}^\sigma, \dots, \bar{w}_{j_1 j_2 \dots j_r}^\sigma)$$

by

$$\bar{y}^i([J_0^r \zeta]) = y^i(J_0^r \zeta), \quad \bar{w}_{j_1 j_2 \dots j_k}^\sigma([J_0^r \zeta]) = w_{j_1 j_2 \dots j_k}^\sigma(J_0^r \zeta). \tag{3.16}$$

Then the pair  $(\tilde{W}, \tilde{\Phi})$  is the associated chart on  $P_n^r Y$ . In terms of  $(W, \Phi)$  and  $(\tilde{W}, \tilde{\Phi})$  the quotient projection  $\rho_n^r$  is expressed by the equations

$$\bar{y}^i \circ \rho_n^r = y^i, \quad \bar{w}_{j_1 j_2 \dots j_k}^\sigma \circ \rho_n^r = w_{j_1 j_2 \dots j_k}^\sigma. \tag{3.17}$$

Consider a point  $J_0^r \zeta \in W$ , and the vector subspace of the tangent space  $T_{\rho_n^r(J_0^r \zeta)} P_n^r Y$  spanned by the vectors  $T_{J_0^r \zeta} \rho_n^r \cdot \Delta_i(J_0^r \zeta)$ , where the vectors  $\Delta_i(J_0^r \zeta)$  are defined by (3.13) and (2.5). Indeed, this vector subspace is independent of the choice of a chart used in the definition of  $d_i$ . It follows from (3.13) and (3.17) that the vector field  $\Delta_i$  is  $\rho_n^r$ -projectable, and its  $\rho_n^r$ -projection is the vector field

$$\tilde{\Delta}_i = \frac{\partial}{\partial \tilde{y}^i} + \sum_{p=0}^r \sum_{j_1 \leq j_2 \leq \dots \leq j_p} \tilde{w}_{j_1 j_2 \dots j_p}^\sigma \frac{\partial}{\partial \tilde{w}_{j_1 j_2 \dots j_p}^\sigma}.$$

Thus, we have the following commutative diagram:

$$\begin{array}{ccc} \text{Imm } T_n^r & \xrightarrow{\Delta_i} & T \text{Imm } T_n^{r-1} \\ \downarrow \rho_n^r & & \downarrow T \rho_n^r \\ P_n^r Y & \xrightarrow{\tilde{\Delta}_i} & T P_n^{r-1} Y \end{array}$$

From now on we adopt the standard convention for writing fibered coordinates, and we omit the tilde over the coordinate functions on the left in (3.16). Then the coordinate functions of the chart  $(\bar{W}, \bar{\Phi})$  will be denoted simply by  $\bar{\Phi} = (y^i, w^\sigma, w_{j_1}^\sigma, w_{j_1 j_2}^\sigma, \dots, w_{j_1 j_2 \dots j_r}^\sigma)$ .

Let us consider two charts  $(V, \psi)$ ,  $\psi = (y^A)$ , and  $(\bar{V}, \bar{\psi})$ ,  $\bar{\psi} = (\bar{y}^A)$ , such that  $V \cap \bar{V} \neq \emptyset$ , and the associated charts  $(V_n^r, \psi_n^r)$  and  $(\bar{V}_n^r, \bar{\psi}_n^r)$  on  $\text{Imm } T_n^r Y$ . The transformation equations for the corresponding associated charts on  $P_n^r Y$  are given by  $\bar{w}_{i_1 i_2 \dots i_k i_{k+1}}^v = Q_{i_{k+1}}^p \Delta_p \bar{w}_{i_1 i_2 \dots i_k}^v$  (Eq. (3.15)).

#### 4. Scalar invariants of $(r, n)$ -velocities

Our aim in this section will be to describe all continuous  $L_n^r$ -invariant, real-valued functions on the manifold of  $(r, n)$ -velocities  $T_n^r Y$ .

As in the case of regular  $(r, n)$ -velocities, we denote by  $\rho_n^r : T_n^r Y \rightarrow T_n^r Y / L_n^r$  the canonical quotient projection. The quotient set  $T_n^r Y / L_n^r$  will be considered with its canonical topological structure; then  $\rho_n^r$  is an open mapping. The set  $\text{Imm } T_n^r Y$  is an open, dense, subset of  $T_n^r Y$ . We have the canonical projection  $\pi_n^r : T_n^r Y / L_n^r \rightarrow Y$ , as well as its restriction  $\pi_n^r : \text{Imm } T_n^r Y / L_n^r \rightarrow Y$  to the  $(r, n)$ -Grassmann bundle  $P_n^r Y = \text{Imm } T_n^r Y / L_n^r$ , which are both continuous. These mappings define a commutative diagram

$$\begin{array}{ccc} \text{Imm } T_n^r Y & \rightarrow & T_n^{r-1} Y \\ \downarrow & & \downarrow \\ P_n^r Y & \rightarrow & T_n^r Y / L_n^r \\ \downarrow & & \downarrow \\ Y & \rightarrow & Y \end{array}$$

$P_n^r Y$  is an open, dense subset of  $T_n^r Y / L_n^r$ . Indeed  $P_n^r Y$  is open in  $T_n^r Y / L_n^r$  by the definition of the quotient topology, since  $\text{Imm } T_n^r Y = (\rho_n^r)^{-1}(P_n^r Y)$  is open in  $T_n^r Y$ . If  $[J_0^r \chi_0] \in T_n^r Y / L_n^r$  is such that  $[J_0^r \chi_0] \notin P_n^r Y$ , and  $W$  is a neighborhood of  $[J_0^r \chi_0]$ , then  $(\rho_n^r)^{-1}(W)$

is an open set in  $T_n^r Y$  containing  $[J_0^r \chi_0]$  as a subset. Since  $\text{Imm } T_n^r Y$  is dense in  $T_n^r Y$ ,  $(\rho_n^r)^{-1}(W) \cap \text{Imm } T_n^r Y$  is a nonempty open subset of  $\text{Imm } T_n^r Y$ , and since  $\rho_n^r$  is open, the set  $\rho_n^r((\rho_n^r)^{-1}(W) \cap \text{Imm } T_n^r Y)$  is open in  $P_n^r Y$ . But  $\rho_n^r((\rho_n^r)^{-1}(W) \cap \text{Imm } T_n^r Y) \subset W$  which means that  $W$  contains an element of the set  $P_n^r Y$ .

Any continuous function on a subset of  $P_n^r Y$  defines, when composed with the quotient projection  $\rho_n^r: \text{Imm } T_n^r Y \rightarrow P_n^r Y$ , an  $L_n^r$ -invariant, continuous function on the corresponding subset of  $\text{Imm } T_n^r Y$ , and vice versa, any  $L_n^r$ -invariant, continuous function on an open,  $L_n^r$ -invariant subset of  $P_n^r Y$  can be factored through  $\rho_n^r$ . Since the values of a continuous, real-valued function on  $T_n^r Y/L_n^r$  are uniquely determined by its values on  $P_n^r Y$ , the projection  $\rho_n^r$  is the *basis of  $L_n^r$ -invariant functions* on  $T_n^r Y$ .

It is now clear that our problem of finding all continuous  $L_n^r$ -invariant, real-valued function on  $T_n^r Y$  is equivalent with the problem of finding continuous functions on open subset of the quotient  $T_n^r Y/L_n^r$ . This gives rise to the problem of *continuous prolongation* of functions on  $P_n^r Y$  to the quotient space  $T_n^r Y/L_n^r$ .

First we need to discuss separability of the points on  $T_n^r Y/L_n^r$ . It is easily seen that the quotient topology on  $T_n^r Y/L_n^r$  is *not* Hausdorff.

Note that any two points  $[J_0^r \chi_0], [J_0^r \chi] \in T_n^r Y/L_n^r$  such that  $\chi_0(0) \neq \chi(0)$ , can always be separated by open sets. This follows from the continuity of the quotient projection of  $\pi_n^r$ , and from separability of  $Y$ . To study the situation in the fibers, we prove the following lemma.

**Lemma 4.** *Let  $y \in Y$  be a point,  $(V, \psi)$ ,  $\psi = (y^A)$  a chart at  $y$ , and  $J_0^r \chi_0 \in (\tau_n^{r,0})^{-1}(y)$  the  $(r, n)$ -velocity with target  $y$  defined by  $J_0^r \chi_0 = (y^A, 0, 0, \dots, 0)$  in the associated chart. Then any  $L_n^r$ -invariant neighborhood of  $J_0^r \chi_0$  contains the fiber  $(\tau_n^{r,0})^{-1}(y)$ .*

*Proof.* The fiber  $(\tau_n^{r,0})^{-1}(y) = (\rho_n^{r,0})^{-1}((\pi_n^{r,0})^{-1}(y))$  over  $y \in Y$  in  $T_n^r Y$  is endowed with the induced chart  $(V_n^r, \psi_n^r)$ ,  $\psi_n^r = (y^A, y_{j_1}^A, y_{j_1 j_2}^A, \dots, y_{j_1 j_2 \dots j_r}^A)$ . The coordinates  $\bar{y}^A, \bar{y}_{j_1 j_2 \dots j_s}^A$  of the points of the orbit  $[J_0^r \chi_0]$  are given by (2.16),

$$\bar{y}^A = y^A, \quad \bar{y}_{j_1 j_2 \dots j_s}^A = \sum_{p=1}^s \sum_{(l_1, l_2, \dots, l_p)} a_{l_1}^{j_1} a_{l_2}^{j_2} \dots a_{l_p}^{j_p} y_{j_1 j_2 \dots j_p}^A,$$

where  $J_0^r \alpha \in L_n^r$ ,  $J_0^r \alpha = (a_{j_1}^i, a_{j_1 j_2}^i, \dots, a_{j_1 j_2 \dots j_r}^i)$ . Thus,  $\bar{y}^A = y^A, \bar{y}_{j_1 j_2 \dots j_s}^A = 0$ , which means that the orbit  $[J_0^r \chi_0]$  consists of a single point. Let  $W$  be an  $L_n^r$ -invariant neighborhood of the point  $J_0^r \chi_0$ . We show that each orbit in  $(\tau_n^{r,0})^{-1}(y)$  has a nonempty intersection with  $W$ . Then we apply  $L_n^r$ -invariance to obtain the inclusion  $(\tau_n^{r,0})^{-1}(y) \subset W$ .

Let us consider an arbitrary element  $J_0^r \chi = (y^A, y_{j_1}^A, y_{j_1 j_2}^A, \dots, y_{j_1 j_2 \dots j_r}^A) \in (\tau_n^{r,0})^{-1}(y)$ , and a one-parameter family of velocities  $J_0^r \chi \circ J_0^r \beta_\tau$  in  $(\tau_n^{r,0})^{-1}(y)$  defined in components by

$$\beta_\tau = (\beta_\tau^i, \beta_\tau^i(t^1, t^2, \dots, t^n) = \tau t^i,$$

where  $0 \leq \tau \leq 1$ . Then  $J_0^r \beta_\tau = (\tau \delta_j^i, 0, 0, \dots, 0)$ , and by (2.16), the  $L_n^r$ -orbit of  $J_0^r \chi$  contains the points  $J_0^r \chi \circ J_0^r \beta_\tau = (\bar{y}^A, \bar{y}_{j_1}^A, \bar{y}_{j_1 j_2}^A, \dots, \bar{y}_{j_1 j_2 \dots j_r}^A)$  given by  $\bar{y}^A = y^A, \bar{y}_{i_1 i_2 \dots i_s}^A = \tau^s \bar{y}_{i_1 i_2 \dots i_s}^A$ . Clearly, for sufficiently small  $\tau$ ,  $J_0^r \chi \circ J_0^r \beta_\tau \in W$ .



This shows that the orbits passing through any neighborhood of the point  $J_0^r \chi_0$ , where  $\chi_0(0) = y$ , fill the whole fiber  $(\tau_n^{r,0})^{-1}(y)$ .  $\square$

Consider a point  $y \in Y$ , a chart  $(V, \psi), \psi = (y^A)$  at  $y$ , and the  $L_n^r$ -orbit  $[J_0^r \chi_0]$  of the velocity  $J_0^r \chi_0 = (y^A, 0, 0, \dots, 0) \in (\tau_n^{r,0})^{-1}(y)$ . Lemma 4 shows that any neighborhood of the orbit  $[J_0^r \chi_0] \in T_n^r Y / L_n^r$  contains the fiber  $(\pi_n^r)^{-1}(y)$  in  $T_n^r Y / L_n^r$  over  $y$ . This proves, in particular, that no point of  $(\pi_n^r)^{-1}(y)$  can be separated from  $[J_0^r \chi_0]$  by open sets.

This gives us the following theorem saying that if a continuous invariant is defined on a fiber in  $T_n^r Y$ , then it is constant along this fiber.

**Theorem 3.** *Let  $W$  be an open,  $L_n^r$ -invariant set in  $\text{Imm } T_n^r Y, f : W \rightarrow \mathbb{R}$  an  $L_n^r$ -invariant function. Assume that  $W$  contains two regular velocities  $J_0^r \zeta, J_0^r \chi$  with common target  $y = \zeta(0) = \chi(0)$  such that  $f(J_0^r \zeta) \neq f(J_0^r \chi)$ . Then  $f$  cannot be continuously prolonged to the fiber  $(\tau_n^{r,0})^{-1}(y) \subset \text{Imm } T_n^r Y$ .*

*Proof.* Indeed, since  $\mathbb{R}$  is Hausdorff, any continuous,  $L_n^r$ -invariant, real-valued function takes the same value at the points which cannot be separated by open sets. Assume that  $f$  can be prolonged to the fiber  $(\tau_n^{r,0})^{-1}(y) \subset \text{Imm } T_n^r Y$ . Then by Lemma 4,  $f$  is equal along the fiber  $\tau_n^{r,0}(y)$  to  $f(J_0^r \chi_0) = \text{const}$ , which is a contradiction.  $\square$

In particular, none of the  $L_n^r$ -invariant functions  $w_{j_1 j_2 \dots j_k}^\sigma$  (Theorem 2) can be prolonged to a fiber  $(\tau_n^{r,0})^{-1}(y)$ .

Now it is immediate that each  $L_n^r$ -invariant function on  $T_n^r Y$  is trivial in the following sense.

**Corollary 6.** *A, continuous function  $f : T_n^r Y \rightarrow \mathbb{R}$  is  $L_n^r$ -invariant if and only if  $f = F \circ \tau_n^{r,0}$ , where  $F : Y \rightarrow \mathbb{R}$  is a continuous function.*

**Appendix A. Regular  $(2, n)$ -velocities**

As before,  $Y$  denotes a smooth manifold of dimension  $n + m$ . In this section we consider the manifold  $\text{Imm } T_n^2 Y$  of regular  $(2, n)$ -velocities on  $Y$ , and the Grassmann bundle  $P_n^2 Y$ . We wish to collect in an explicit form all basic formulas concerning charts and invariants in this case, which will be important for applications.

If  $(V, \psi), \psi = (y^A)$ , is a chart on  $Y$ , define  $V_n^2 = (\tau_n^{2,0})^{-1}(V)$  and  $\psi_n^2 = (y^A, y_i^A, y_{ij}^A)$  where  $1 \leq A \leq n + m, 1 \leq i \leq j \leq n$ , by the formulas  $y^A(J_0^2 \zeta) = y^A(\zeta(0)), y_i^A(J_0^2 \zeta) = D_i y^A(\zeta)(0), y_{ij}^A(J_0^2 \zeta) = D_i D_j (y^A \zeta)(0)$ . If  $(\bar{V}, \bar{\psi}), \bar{\psi} = (\bar{y}^A)$ , is another chart on  $Y$ , and the transformation equations are written as  $\bar{y}^A = F^A(y^B)$ , then

$$\bar{y}^A = F^A(y^B), \quad \bar{y}_i^A = \frac{\partial F^A}{\partial y^B} y_i^B, \quad \bar{y}_{ij}^A = \frac{\partial^2 F^A}{\partial y^B \partial y^C} y_i^B y_j^C + \frac{\partial F^A}{\partial y^B} y_{ij}^B \tag{A.1}$$

on  $V_n^2 \cap \bar{V}_n^2$  (see (2.9)–(2.11)). If  $f : V_n^1 \rightarrow \mathbb{R}$  is a smooth function, we define a function  $d_i f : V_n^2 \rightarrow \mathbb{R}$  by

$$d_i f = \frac{\partial f}{\partial y^A} y_i^A + \frac{\partial f}{\partial y_j^A} y_{ij}^A.$$

This function is called the *i*th formal derivative of  $f$ . In particular,  $d_i y^A = y_i^A$ ,  $d_i y_j^A = y_{ij}^A$ .

By definition,  $\text{rank}(y_s^B(J_0^2 \zeta)) = n$  at every point  $J_0^2 \zeta \in V_n^2$ . Thus, there exists a subsequence  $I = (A_1, A_2, \dots, A_n)$  of the sequence  $(1, 2, \dots, n, n + 1, n + m)$  such that  $\det(y_i^{A_i}(J_0^2 \zeta)) \neq 0$ . Denote  $V_n^{2(I)} = \{J_0^2 \zeta \in V_n^2 \mid \det(y_i^{A_i}(J_0^2 \zeta)) \neq 0\}$ . If  $\psi_n^{2(I)}$  is the restriction of  $\psi_n^2$  to  $V_n^{2(I)}$ , then the pair  $(V_n^{2(I)}, \psi_n^{2(I)})$ ,  $\psi_n^{2(I)} = (y^A, y_i^A, y_{ij}^A)$ , is a chart on  $\text{Imm } T_n^2 Y$ , and

$$\bigcup_I V_n^{2(I)} = V_n^2.$$

By (2.14), the group multiplication  $(J_0^2 \alpha, J_0^2 \beta) \rightarrow J_0^r \alpha \circ J_0^r \beta$  in the second differential group  $L_n^2$  of  $\mathbb{R}^n$  is given in the canonical coordinates by

$$c_i^k = b_i^p a_p^k, \quad c_{ij}^k = b_{ij}^p a_p^k + b_j^q a_{pq}^k. \tag{A.2}$$

Indeed, in this formula  $a_p^k, a_{pq}^k$  (resp.  $b_i^p, b_{ij}^p$ , resp.  $c_i^k, c_{ij}^k$ ) are the coordinates of  $J_0^2 \alpha$  (resp.  $J_0^r \beta$ , resp.  $J_0^r \alpha \circ J_0^r \beta$ ).  $L_n^2$  acts on  $\text{Imm } T_n^2 Y$  smoothly to the right by the jet composition  $(J_0^2 \zeta \circ J_0^2 \alpha) \rightarrow J_0^2 \zeta \circ J_0^2 \alpha$ . This action is expressed by

$$\bar{y}^A = y^A, \quad \bar{y}_i^A = y_s^A a_i^s, \quad \bar{y}_{ij}^A = y_{pq}^A a_i^p a_j^q + y_p^A a_{ij}^p, \tag{A.3}$$

where  $y^A, y_i^A, y_{ij}^A$  are the coordinates of a velocity  $J_0^2 \zeta$ , and  $\bar{y}^A, \bar{y}_i^A, \bar{y}_{ij}^A$  are the coordinates of the transformed velocity  $J_0^2 \zeta \circ J_0^2 \alpha$ .

Now we are going to construct an atlas on  $\text{Imm } T_n^2 Y$ , adapted to this group action. Given a chart  $(V, \psi)$ ,  $\psi = (y^A)$ , we note that the action (A.3) preserves each of the sets  $V_n^{2(I)}$ . Indeed, if  $J_0^2 \zeta \in V_n^{2(I)}$ , then by definition, the matrix  $y_j^{A_i} = y_j^{A_i}(J_0^2 \zeta)$  is of maximal rank, and the second equation of (A.3) implies that the matrix  $\bar{y}_j^{A_i} = y_j^{A_i}(J_0^2(\zeta \alpha))$  of the transformed point is also of maximal rank.

Consider for example the case  $I = (1, 2, \dots, n)$ . Then  $\det(y_j^i) \neq 0$  for  $1 \leq i, j \leq n$  (i.e. on  $V_n^{2(I)}$ ). We define smooth functions  $z_j^i : V_n^{2(I)} \rightarrow \mathbb{R}$  by  $z_p^i y_j^p = \delta_j^i$ . These functions form a regular matrix on  $V_n^{2(I)}$ . Eqs. (A.3) then give for  $A = k = 1, 2, \dots, n$

$$z_p^k \bar{y}_i^p = a_i^k, \quad z_s^k \bar{y}_{ij}^s = z_s^k y_{pq}^s a_i^p a_j^q + z_s^k y_p^s a_{ij}^p = z_s^k y_{pq}^s z_r^p \bar{y}_i^r z_t^q \bar{y}_j^t + a_{ij}^k,$$

and for  $A = \sigma = n + 1, n + 2, \dots, m$

$$\begin{aligned} \bar{y}^A &= y^A, & \bar{y}_i^A &= y_s^A z_p^s \bar{y}_i^p, \\ \bar{y}_{ij}^A &= y_{pq}^A z_s^p \bar{y}_i^s z_t^q \bar{y}_j^t + y_k^A (z_s^k \bar{y}_{ij}^s - z_s^k y_{pq}^s z_r^p \bar{y}_i^r z_t^q \bar{y}_j^t). \end{aligned}$$

Since the second formula gives us the relation  $\bar{z}_j^i \bar{y}_i^\sigma = z_j^s y_s^\sigma$ , and the third one implies

$$\bar{z}_u^i \bar{z}_v^j (\bar{y}_{ij}^\sigma - \bar{z}_s^k \bar{y}_{pq}^\sigma \bar{y}_{ij}^s) = y_{pq}^\sigma z_u^p z_v^q - z_s^k y_k^\sigma y_{pq}^s z_u^p z_v^q = z_u^p z_v^q (y_{pq}^\sigma - z_s^k y_k^\sigma y_{pq}^s),$$

we finally get

$$\bar{y}^A = y^A, \quad \bar{z}_j^i \bar{y}_i^\sigma = z_j^s y_s^\sigma,$$

and  $\bar{z}_u^i \bar{z}_v^j (\bar{y}_{ij}^\sigma - \bar{z}_s^k \bar{y}_{pq}^\sigma \bar{y}_{ij}^s) = z_u^p z_v^q (y_{pq}^\sigma - z_s^k y_k^\sigma y_{pq}^s)$ . Therefore, the functions

$$y^i, \quad w^\sigma = y^\sigma, \quad w_i^\sigma = z_i^s y_s^\sigma, \quad w_{ij}^\sigma = z_i^p z_j^q (y_{pq}^\sigma - z_s^k y_k^\sigma y_{pq}^s) \tag{A.4}$$

are constant along the  $L_n^2$ -orbits in  $V_n^{2(I)} \subset \text{Imm } T_n^2 Y$ , and the functions  $y^i, w^\sigma, w_i^\sigma, w_{ij}^\sigma, y_j^i, y_{jk}^i$  define a new chart on the set  $V_n^{2(I)}$  adapted to the group action of  $L_n^2$ . The right action (A.3) is expressed in terms of this new chart by  $\bar{y}^i = y^i, \bar{w}^\sigma = w^\sigma, \bar{w}_{ij}^\sigma = w_{ij}^\sigma, \bar{y}_i^k = y_s^k a_i^s, \bar{y}_{ij}^k = y_{pq}^k a_i^p a_j^q + y_{pq}^k a_{ij}^p$ . The functions (A.4) are components of the quotient projection  $\rho_n^2$  of the manifold of regular  $(2, n)$ -velocities  $\text{Imm } T_n^2 Y$  onto the  $(2, n)$ -Grassmann bundle  $P_n^2 Y$ , and form a basis of  $L_n^2$ -invariant functions on  $V_n^{2(I)}$ .

A direct interpretation of the coordinate functions (A.4) is obtained as follows. Let  $(V, \psi), \psi = (x^i, y^\sigma)$ , be a chart on  $Y$ , and let  $J_0^2 \zeta \in V_n^{2(I)}$ . We assign to the 2-jet  $J_0^2 \zeta$  an element  $J_0^2 \alpha \in L_n^2$  by means of a representative  $\alpha$  satisfying, in addition to the condition  $\alpha(0) = 0$ , the following two conditions  $a_i^s(J_0^2 \alpha) = D_i \alpha^s(0) = y_i^s(J_0^2 \zeta), a_{ij}^s(J_0^2 \alpha) = D_i D_j \alpha^s(0) = y_{ij}^s(J_0^2 \zeta)$ . Then it is easily seen that

$$\begin{aligned} a_r^i(J_0^2 \alpha^{-1}) &= D_r(\alpha^{-1})^i(0) = z_r^i(J_0^2 \zeta), \\ a_{rs}^i(J_0^2 \alpha^{-1}) &= D_r D_s(\alpha^{-1})^i(0) = -z_r^j(J_0^2 \zeta) z_s^k a_r^i(J_0^2 \zeta) y_{jk}^p(J_0^2 \zeta), \end{aligned}$$

and we get for the coordinates of the 2-jet  $J_0^2(\zeta \circ \alpha^{-1}) \in V_n^{2(I)}$ , by (A.4),

$$\begin{aligned} y^i(J_0^2(\zeta \circ \alpha^{-1})) &= y^i(J_0^2 \zeta), \quad y_i^k(J_0^2(\zeta \circ \alpha^{-1})) = \delta_i^k, \quad y_{ij}^k(J_0^2(\zeta \circ \alpha^{-1})) = 0, \\ y^\sigma(J_0^2(\zeta \circ \alpha^{-1})) &= w^\sigma(J_0^2 \zeta), \quad y_i^\sigma(J_0^2(\zeta \circ \alpha^{-1})) = w_i^\sigma(J_0^2 \zeta), \\ y_{ij}^\sigma(J_0^2(\zeta \circ \alpha^{-1})) &= w_{ij}^\sigma(J_0^2 \zeta), \end{aligned}$$

where  $k = 1, 2, \dots, n \quad \sigma = n+1, n+2, \dots, m$ . This represents the desired interpretation of the functions (A.4) as jet coordinates of the 2-jets  $J_0^2 \zeta \circ J_0^2 \alpha$ , with  $J_0^2 \alpha$  determined by the considered chart.

One can determine the transformation formulas from  $\psi_n^2(J_0^2(\zeta \circ \alpha^{-1}))$  to  $\bar{\psi}_n^2(J_0^2(\zeta \circ \bar{\alpha}^{-1}))$ , with obvious meaning of  $\bar{\alpha}$ . These formulas illustrate the well-known fact that the higher-order Grassmann bundles have a relatively complicated smooth structure. Consider an element  $J_0^2 \zeta \in V_n^{2(I)} \cap \bar{V}_n^{2(I)}$ . The corresponding computations for  $J_0^2 \zeta \in V_n^{2(I)} \cap \bar{V}_n^{2(J)}$  with arbitrary  $I, J$  are quite analogous. We have

$$\begin{aligned} \bar{\psi}_n^2(J_0^2(\zeta \circ \bar{\alpha}^{-1})) &= \bar{\psi}_n^2(J_0^2(\zeta \circ \alpha^{-1} \circ \alpha \bar{\alpha}^{-1})) = \bar{\psi}_n^2(J_0^2(\zeta \circ \alpha^{-1})) \circ J_0^2(\alpha \bar{\alpha}^{-1}) \\ &= \bar{\psi}_n^2(\psi_n^2)^{-1}(\psi_n^2(J_0^2(\zeta \circ \alpha^{-1}) \circ J_0^2(\alpha \bar{\alpha}^{-1}))). \end{aligned}$$

To derive explicit expressions, one has to substitute for the group multiplication (A.2), the group action (A.3), and the transformation (A.1) in this formula. Denoting

$$P_s^q = \frac{\partial F^q}{\partial y^s} + \frac{\partial F^q}{\partial y^\nu} w_s^\nu,$$

we get a regular matrix  $P = (P_s^q)$ . Let  $Q = P^{-1} = (Q_j^i)$  be its inverse. Then

$$\bar{y}_i^q = P_s^q y_i^s, \quad \bar{z}_i^q = Q_j^s z_i^s.$$

After a tedious but straightforward calculation we get the following result. Given the transformation equations on  $Y$ ,  $\bar{y}^k = F^k(y^\rho, y^\nu)$ ,  $\bar{y}^\sigma = F^\sigma(y^\rho, y^\nu)$ , then on  $V_n^{2(I)} \cap \bar{V}_n^{2(J)}$ ,

$$\begin{aligned} \bar{y}^k &= F^k(y^\rho, y^\nu), \quad \bar{w}^\sigma = F^\sigma(y^\rho, y^\nu), \quad \bar{w}_i^\sigma = Q_i^p \left( \frac{\partial F^\sigma}{\partial y^\rho} + \frac{\partial F^\sigma}{\partial w^\nu} w_p^\nu \right), \\ \bar{w}_{ij}^\sigma &= Q_i^p Q_j^q \left( \frac{\partial^2 F^\sigma}{\partial y^\rho \partial y^q} + \frac{\partial^2 F^\sigma}{\partial y^\rho \partial w^\nu} w_q^\nu + \frac{\partial^2 F^\sigma}{\partial w^\nu \partial y^q} w_p^\nu \right. \\ &\quad \left. + \frac{\partial^2 F^\sigma}{\partial w^\mu \partial w^\nu} w_p^\mu w_q^\nu + \frac{\partial F^\sigma}{\partial w^\nu} w_{pq}^\nu \right) \\ &\quad - Q_i^q Q_j^b Q_k^p \left( \frac{\partial F^\sigma}{\partial y^\rho} + \frac{\partial F^\sigma}{\partial w^\nu} w_p^\nu \right) \\ &\quad \times \left( \frac{\partial^2 F^k}{\partial y^a \partial y^b} + \frac{\partial^2 F^k}{\partial y^a \partial w^\sigma} w_b^\sigma + \frac{\partial^2 F^k}{\partial w^\sigma \partial y^b} w_a^\sigma \right. \\ &\quad \left. + \frac{\partial^2 F^k}{\partial w^\sigma \partial w^\lambda} w_a^\sigma w_b^\lambda + \frac{\partial F^k}{\partial w^\lambda} w_{ab}^\lambda \right). \end{aligned}$$

Clearly, these equations represent the transformation formulas for the induced charts on the  $(2, n)$ -Grassmann bundle  $P_n^2 Y$ .

## References

- [1] P. Dedecker, On the generalization of symplectic geometry to multiple integrals in the calculus of variations, *Lecture Notes in Mathematics*, Vol. 570 (Springer, Berlin) 395–456.
- [2] J. Dieudonné, *Elements d'Analyse 3* (Gauthier-Villars, Paris, 1970).
- [3] D.R. Grigore, A generalized Lagrangian formalism in particle mechanics and classical field theory, *Fortschr. d. Phys.* 41 (1993) 569–617.
- [4] D.R. Grigore and O. Popp, On the Lagrange–Souriau form in classical field theory, *Math. Bohemica*, to appear.
- [5] P. Horváthy, Variational formalism for spinning particles, *JMP* 20 (1974) 49–52.
- [6] J. Klein, Espaces variationnels et Mécanique, *Ann. Inst. Fourier (Grenoble)* 12 (1962) 1–124.
- [7] I. Kolár, P. Michor and J. Slovák, *Natural Operations in Differential Geometry* (Springer, Berlin, 1993).
- [8] I.S. Krasilschik, A.M. Vinogradov and V.V. Lychagin, *Geometry of Jet Spaces and Nonlinear Differential Equations* (Gordon and Breach, New York, 1986).
- [9] D. Krupka, Local invariants of linear connections, *Colloq. Math. Soc. János Bolyai*, 31. *Differential Geometry* (Budapest, 1979) (North-Holland, Amsterdam, 1982) 349–369.
- [10] D. Krupka, Natural Lagrangian structures, Semester on Diff. Geom. (Banach Center, Warsaw, 1979) *Banach Center Publications* 12 (1984) 185–210.
- [11] M. Krupka, Orientability of higher order Grassmannians, *Math. Slovaca* 44 (1994) 107–115.

- [12] M. Krupka, Natural operators on vector fields and vector distributions, Ph.D. Dissertation, Faculty of Science, Masaryk University, Brno, Czech Republic (1995)
- [13] D. Krupka and J. Janyška, *Lectures on Differential Invariants* (Brno University, Czech Republic, 1990).
- [14] A. Nijehuis, Natural bundles and their general properties, *Differential Geometry, in honour of K. Yano* (Kinokuniya, Tokyo, 1972) 317–334.
- [15] J.M. Souriau, *Structure des Systemes Dynamiques* (Dunod, Paris, 1970).